

Copernicus Emergency Management Service

The Global Flood Monitoring ensemble flood product

17th EFAS Annual meeting 2022



Presented by Dragana Milinkovic (EODC) 28 09 2022

Motivation for Global Floods Monitoring (GFM)

Due to:

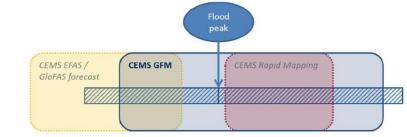
- No constant automatic monitoring,
- Required user activation,
- Often late arrival of activation requests (missing flood onset/peak), and
- Limited resources made it impossible to map all floods

JRC initiated the expansion of the CEMS with the new GFM component.

GFM: A global near real time (NRT) flood monitoring system based on the Copernicus Sentinel-1 SAR mission.



https://emergency.copernicus.eu/



Key specifications

The GFM product is specifically designed to address three major user requirements for floods:

- providing a continuous global & systematic monitoring,
- significantly enhancing the timeliness,
- improving the effectiveness of activation requests.

GFM's key features are:

- SAR enables all day & all weather conditions flood monitoring
- Near Real Time Flood map provision + regular quality control
 - within 8 hours after a Sentinel-1 data acquisition
- Integration into emergency systems & third party solutions
 - APIs & UIs and notifications services for all products
- High spatial resolution
 - 20 meter pixel sampling
- Complete spatial coverage
 - global (except poles)
- Global flood archive
 - 2015 ongoing



https://emergency.copernicus.eu/

Approach

Flood mapping is carried out in two steps:

- 1. Three independent flood mapping algorithms (run in parallel) generate:
 - Three flood extents.
 - Three associated likelihood of flood detection.
- 2. An ensemble algorithm generates:
 - A combined flood extent based on majority voting.
 - A combined, average likelihood of flood detection.

Caution: What might go wrong?

There are many "<u>water-look-alike</u>" surfaces Static: Tarmac, sand deserts, grasslands, shadows, ... Dynamic: Agricultural fields, wet snow, frozen soils, ...



There are <u>no-sensitivity-areas</u> Dense vegetation, urban areas, etc.



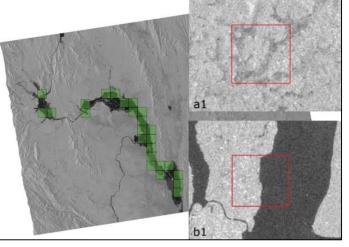
may cause false negatives



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Combining different strategies to increase robustness





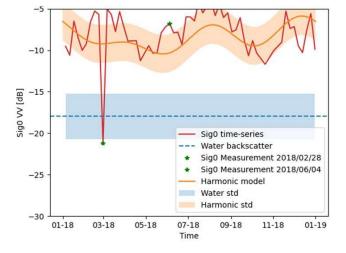
 Hierarchical tile-based thresholding

Kasse

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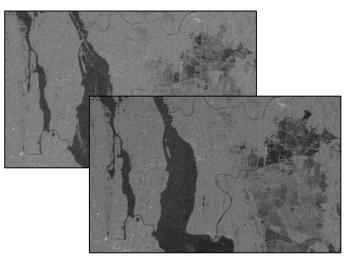
 Post classification and likelihood estimation through fuzzy logicbased refinement





- Per-pixel time series analysis
- Flood as deviation from harmonic model
- Likelihood through probability of opposing class





- Change detection
- Flood as deviating water surface
- Likelihood through probability



Flood Ensemble

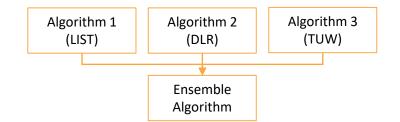
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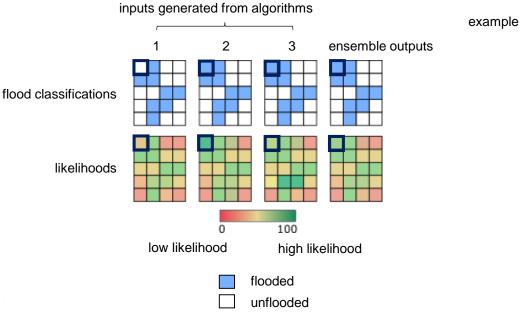
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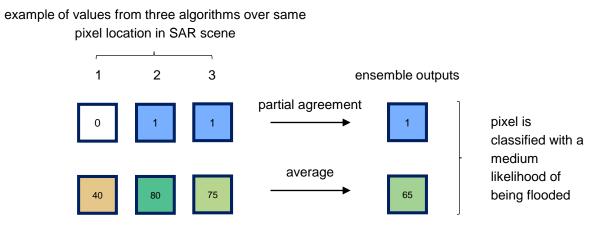
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- Combining flood and likelihood results of all three flood algorithms
- Majority vote decides if a pixel is marked as flood or non-flood
- Final likelihood layer is the arithmetic mean of all likelihoods





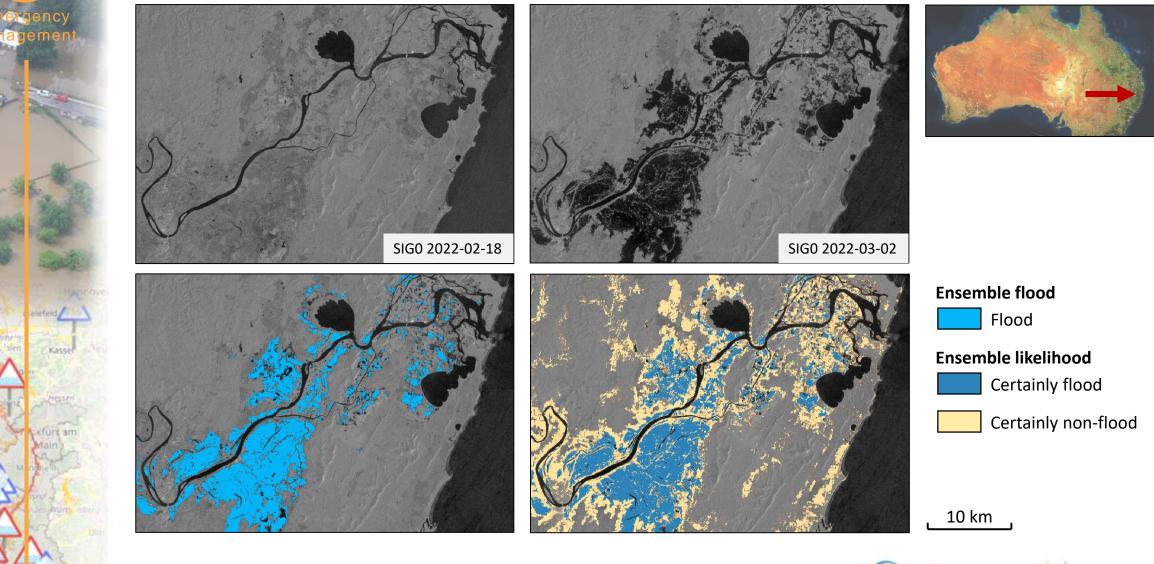




Ensemble Flood Results

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🔊 🐂 Uncertainties & Limitations

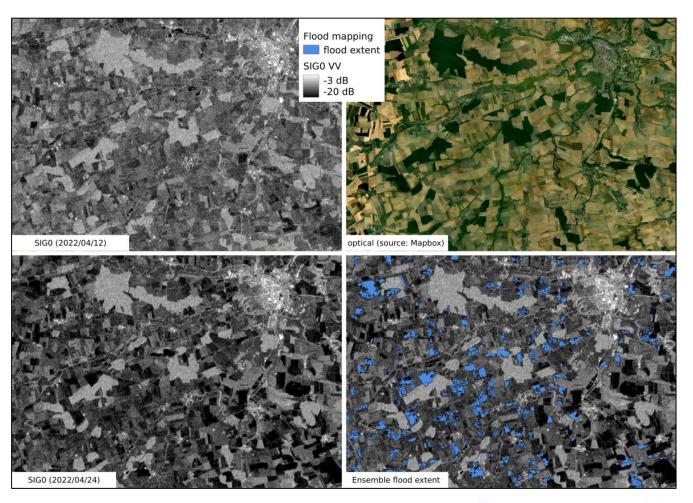
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- Ensemble flood output is a complex scientific data product supported by several novel data layers
- Not all detection errors can be captured
 - Wet snow
 - Frozen soils
 - Agriculture
- Interpret flood pixels using available information
 - Likelihood Layer
 - Exclusion Mask
 - Reference Water
 - Advisory Flags
 - Environmental factors
 - Use local knowledge







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S-1 observed flood extent

 Ensemble flood extent through flood algorithms by DLR, LIST & TUW

S-1 reference water mask

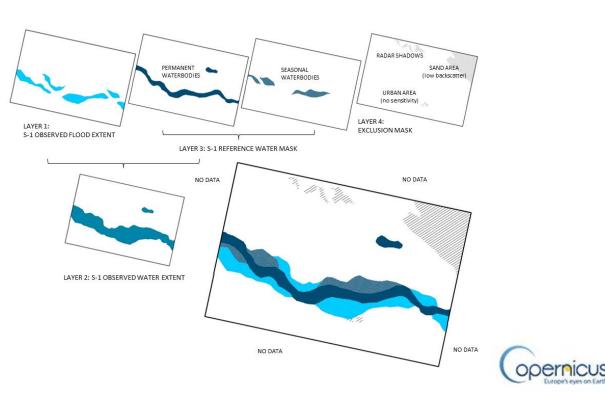
- Based on water algorithms of DLR & LIST
- Permanent & seasonal water

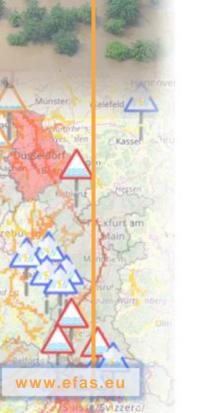
S-1 observed water extent

 Open water extent as combination of flood extent and reference water

European

Commission





Product Output Layers: Water observations

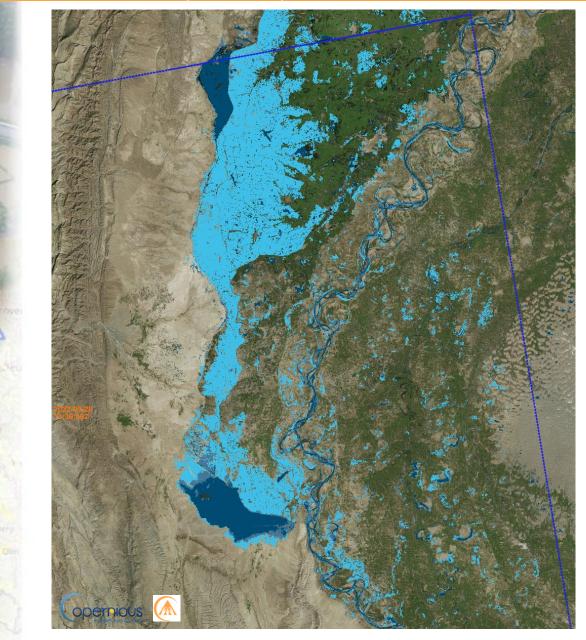


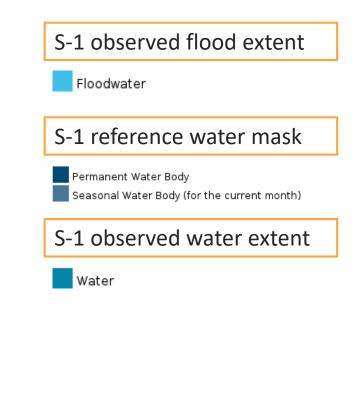
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🔊 📕 Product Output Layers: Contextual Information

Exclusion mask

- Exclusion mask where S1 flood delineation is hampered
- 4 layers:

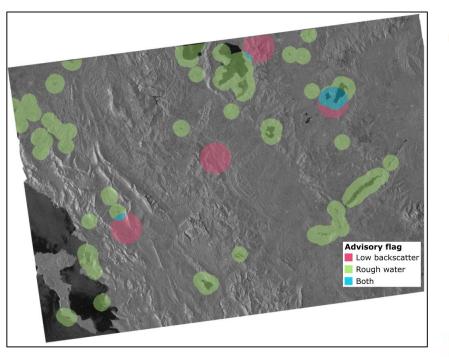
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- No sensitivity
- Low backscatter
- Topographic distortion
- Radar shadows

Likelihood values

 Likelihood values accounting for classification confidence



Advisory flags

- Advisory flags indicating challenging classification circumstances
- Mask dynamic influences
 - Low regional backscatter (snow, ice dryness)
 - Rough water surface (wind)





Reproduct Output Layers: Contextual Information

Flooding in Pakistan, 20.09.2022 GloFAS



Exclusion mask

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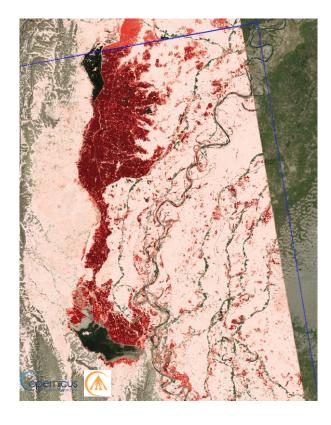
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Exclusion Mask set



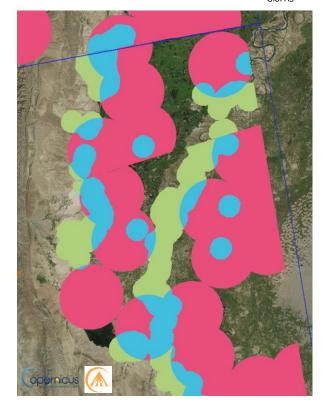
Likelihood values

Low likelihood of flood classification

25%

50%

- 75%
- High likelihood of flood classification



Advisory flags

Low regional backscatter (snow, ice, dryness) Rough water surface (wind) Low regional backscatter and rough water surface





Final Results

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SIG0 2022-02-18 SIG0 2022-03-02

10 km

Ensemble flood

Exclusion mask



Coming up

- Next EFAS release with GFM product integrated
- Improved visualisation & data access features
- Global Flood Archive
- Increased number of use cases and stratified sampling for QA
- Updated permanent/seasonal reference water mask
- Algorithm improvements to address overdetection
- And more to come...



For more insights, please visit the GFM Wiki https://extwiki.eodc.eu/en/GFM **Contact us via** <u>gfm-support@eodc.eu</u>

Thank you for your attention!

